

Lecture 23

CSE 431
Intro to Theory of
Computation

$$\text{TIME}(f(n)) \subseteq \text{NTIME}(f(n)) \subseteq \text{SPACE}(f(n)) \subseteq \text{NSPACE}(f(n)) \subseteq \text{TIME}(2^{O(f(n))})$$

for $f(n) \gg \log_2 n$

$$\bigcup_k \text{TIME}(2^{k \log n})$$

$$L \subseteq NL \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXP \subseteq NEXP$$

$$\Phi \quad \exists x_1, \forall x_2 \exists x_3 \dots \exists x_n \varphi(x_1, \dots, x_n)$$

Formula Game: Played on formula Φ :
for Φ

\exists player wants to make φ have value 1
 \forall player wants to make φ have value 0.

Players take turns setting values of x_i vars.

\exists player sets all $\exists x_i$ variables
 \forall player sets all $\forall x_i$ variables

\exists player has a winning strategy $\Leftrightarrow \Phi$ is true

note: $\neg \Phi$ is true $\Leftrightarrow \neg \exists x_1 \forall x_2 \exists x_3 \dots \exists x_n \varphi(x_1, \dots, x_n)$
 $\Leftrightarrow \forall x_1 \exists x_2 \forall x_3 \dots \forall x_n \neg \varphi(x_1, \dots, x_n)$
 $\Leftrightarrow \exists$ player for $\neg \Phi$ has winning strategy
 $\Leftrightarrow \forall$ player for Φ has a winning strategy

Above is the basic idea for how
to start showing that
deciding guaranteed win in 2-player
games are PSPACE-complete ($n \times n$ checkers
etc.)

Polynomial Hierarchy:

sets of languages Σ_k^P, Π_k^P for integer k

$$\Sigma_k^P = \{ A : A \leq_m^P \{ \text{true formulas in } \exists QBF_k \} \}$$

where $\exists QBF_k = \{ \text{fully quantified Boolean formulas with} \\ \leq k \text{ alternating blocks of quantifiers} \\ \text{beginning with } \exists \}$

$$\Pi_k^P = \{ A : A \leq_m^P \{ \text{true formulas in } \forall QBF_k \} \}$$

where $\forall QBF_k = \{ \text{fully quantified Boolean formulas with} \\ \leq k \text{ alternating blocks of quantifiers} \\ \text{beginning with } \forall \}$

$$\Sigma_1^P = NP \quad \exists x_1 \dots \exists x_n \varphi(x_1 \dots x_n)$$

$$\Pi_1^P = coNP \quad \forall x_1 \dots \forall x_n \varphi(x_1 \dots x_n)$$

Polynomial time hierarchy:

$$PH = \bigcup_k \Sigma_k^P = \bigcup_k \Pi_k^P$$

There are other natural problems with practical importance that are as hard as any problem in class like Σ_2^P

eg. Minimum equivalent DNF (sum of products)
 $\{ \langle F \rangle : F \text{ is a DNF formula that cannot be shortened} \}$

Thm: If $P=NP$ then $PH=P$

Proof idea: if $P=NP$ then we can replace
 $\exists x \varphi(x)$ by some φ' of poly size.
or $\forall x \varphi(x)$ by some φ' of poly size
repeat this k times starting on the inside. \square
Blow-up is fixed exponent depending on k .

Note: key difference between PH and $PSPACE$
is that # of attempts is bounded by
a constant that may depend
on length of the input

Logarithmic Space

Consider the following non-regular language

$$A = \{0^n 1^n : n \geq 0\}$$

TM deciding A : On input x
Space $O(\log n)$ bits
two counters up to length of input
Count # of 0's at start before first 1
Count # of 1's next.
If counts differ or there are more characters before 1st blank reject
else accept.

Let $L = SPACE(\log n) \quad \therefore A \in L$

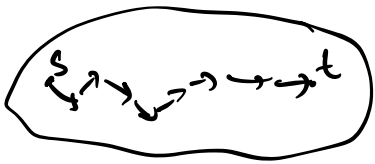
$NL = NSPACE(\log n)$

$$L \subseteq NL \subseteq TIME(2^{O(\log n)}) = P$$

Recall $PATH = \{ \langle G, s, t \rangle : G \text{ is a directed graph with a path from } s \text{ to } t \}$

Thm PATHENL

Proof idea: Guess and verify a path of length $\leq h$ from s to t , one vertex at a time ^{# vertices}



not enough space to actually write down the path.

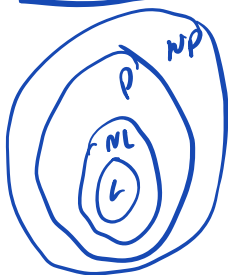
Keep track of: counter for the length
current vertex (and next vertex) $\log_2 h$ bits
 $O(\log_2 n)$ bits

NM:

```

count ← 0
curr ← s
while count ≤ n and curr ≠ t do
  Guess next vertex (neighbor) v
  of curr
  Check if (curr, v) is an edge
  If not then reject
  else curr ← v.
If curr = t then accept
else reject
  
```

Question:



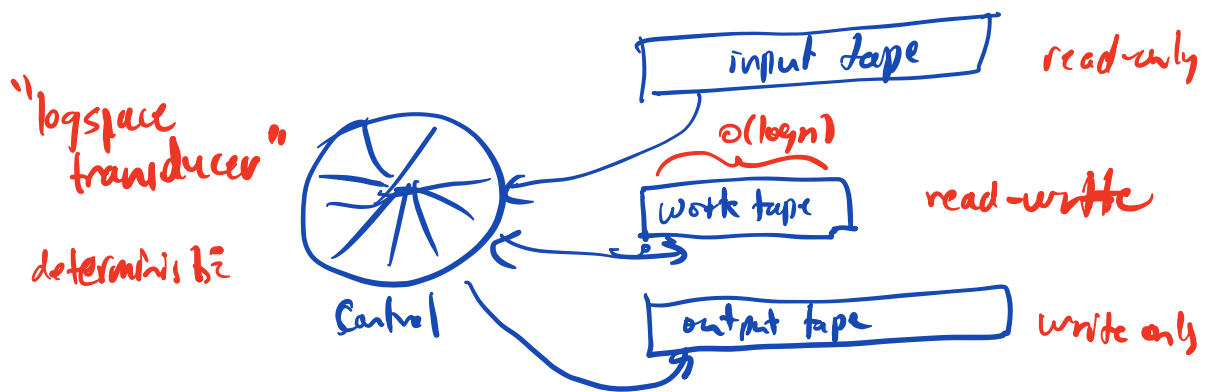
Is $L = NL$?
 $L = P$?
 $NL = P$?
 $NL = NP$?
 $L = NP$?

All of these are open
If $P \neq NP$ then $L \neq NP$
which may be easier to show.

To study these questions we need a finer notion of reduction than \leq_m which allows polynomial slack

For this we need a notion of log-space computable functions

We modify our 2-tape space bounded notion of TM to a 3-tape TM like this:



Defn A function f is logspace computable

iff it is computed by some logspace transducer.

$\Rightarrow f$ is polynomial-time computable (see below)

eg. Consider the SORT function on n , $O(\log n)$ -bit numbers

$SORT(x_1, \dots, x_n) = "x_1 \dots x_n \text{ in sorted order}"$
 ie. $x_{\sigma(1)} \dots x_{\sigma(n)}$ s.t.
 $x_{\sigma(1)} \leq x_{\sigma(2)} \leq \dots \leq x_{\sigma(n)}$
 & a permutation

Claim SORT is logspace computable:

Proof For sorts like quicksort, merge sort use too much space
 Selection sort only needs counters and one or two x_i stored \square

Note: This part is slow $\geq n^2$ time but uses only $O(\log n)$ space

Fact: For any sorting algorithm

$$T \cdot S \in \Omega(n^2)$$

↑ ↑
time space

so this slowdown is unavoidable

Logspace reductions and completeness

Defn $A \leq_m^L B$ iff $A \leq_m B$ by a mapping function that is logspace computable

Thm If $A \leq_m^L B$ then $A \leq_m^P B$

Proof idea: # of configurations of logspace transducer (not counting the output tape which doesn't govern how the TM moves) is $n^{O(1)}$

Defn B is NL-hard iff $\forall A \in NL, A \leq_m^L B$

Defn B is NL-complete iff

- $B \in NL$
- B is NL-hard

Thm PATH is NL-complete

Proof We already showed that $PATH \in NL$

we just need to show NL-hardness

Let $A \in NL$

Claim $A \leq_m^L PATH$

Proof $A \in NL$

$\therefore \exists$ TM M deciding A using $O(\log n)$ space.

M accepts x

$\Rightarrow \exists$ path from C_0 to C_{accept} in directed graph $G_{M,x}$

so $A \leq_m^L PATH$

$x \xrightarrow{f} \langle G, s, t \rangle$

" " "

$G_{M,x} \quad C_0 \quad C_{\text{accept}}$

$x \in A \Leftrightarrow \exists$ path in $G_{M,x}$ from C_0 to C_{accept}

Output is poly size since $2^{O(\log n)}$ nodes.
each edge takes only $O(\log n)$ bits to write down
and is easy to list through edges in order. \square